

Motion Control: Solving Challenging Problems with new Technologies

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What we will cover today



History & evolution of motion

Common challenges in applications



Technology solutions



Future trends in motion

What we will cover today



Servo drives and motors

Drives:

- Analog tuning
- Output for fault
- -> Digital tuning -> Full diagnostics

Motors

• DC Brushed

AC Synchronous

More types of motors to choose from:

->

- Stepper
- Linear
- Direct Drive
- Hygienic







Feedback devices

Started with:

- Low resolution
- Fragile

Moving towards:

- High resolution (µm accuracy)
- Durable
- Serial communication (not just position)
- Network communication

Specialized tools

Laser

• Not just cutting anymore

Mechanical systems

- High accuracy stages
- Hexapod

Robots

- Custom design
- Combine mechanical systems (7th axis)
- Integration with conveyors, vision...









What we will cover today















What we will cover today



3-Technology Solutions



- To show concepts, algorithms, methods, technology, and practice to solve challenges and meet demand
- We need to consider the whole system because, in motion control, all elements are interconnected and act as a compound dynamic system

The technology solutions spines



Let us look at the complete System



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What makes Motion Control Systems



Machine Configurations, architecture, and Interfaces

1- Combining motion control, machine control, and robotics into one controller



With the same controller, same network, same machine interface with the same development tools

Expanding the architecture with integrated vision and safety



Machine Configurations, architecture, and Interfaces

2- Expand machine and automation by integrating vision and safety



With the same controller, same network, same machine interface with the same development tools

Application examples:

Hybrid fast and standard tool control





Laser processing Micromachining Laser marking + more





Example Improvements in components

These will focus on speed, resolution, rates, and power....

Component	Improvement in
Encoder	Resolutions, speed, size, durability, connections, protocols,
Servo Drive	I/O, communication, diagnostics, compensation, algorithms, speed, computation, range and flexibility
Servo Motor	Torque or force/weight, ranges, dynamic response, range
Network, Protocol and connectivity	Stability, resolution, speed and bandwidth, flexibility, the mix of devices and protocols, redundancy, dynamic configuration,
Controllers, Real-time OS and Execution	Computations, multi-core, robust, multitasking,
	Encoder Servo Drive Servo Motor Network, Protocol and connectivity Controllers, Real-time OS and Execution

Improved response, precision, and control of current, velocity, and position

+ Improved development and performance, and expanded (do more)

Faster, Precision machines and precise productions.



EtherCAT.

EtherNet/IP

Recent

Algorithms and software

Servo

- Load, friction, resonance, backlash, velocity real-time estimation
- Velocity and acceleration Feedforward
- Vibration control of resonance and structure
- Adaptive filters
- On the fly switching among torque, velocity, and position control
- Linear and quadratic interpolation
- Control gains switching
- Multi-axes servo tuning
- Dual feedback



Algorithms and software

Controller

- Curve fitting and lookahead
- Al anomaly detection in real-time
- Dynamic trajectory generation
- Custom kinematics
- Advance servo position loop control in the controller
- 1 D, and Multi-dimensional compensation
- Cross coupling and dynamic compensation
- Single resonance and multi resonance control using trajectory for single axis or a 6 dof robot
- High speed and high precision











Development and Tools

Graphical interactive, digital twin, simulation, Sample application, wizard, automated deployment, tuning, ...



What we will cover today



New demands and trends

Industrial Networks

- Higher speed network (GBS)
- Wireless
- Data collection and transfer

Higher accuracy encoders

Demand for smaller products

- Smaller machines
- Smaller tooling
- Extreme accuracy





Artificial Intelligence in Motion

Machine learning

- Collect analyze and utilize data
- Anomaly detection
- Predicting failure before it happens

Samples of failures that is can predict

- Ball screw
 - Guide broken
 - Ball Bearings falling out
 - Contamination
- Conveyor
 - Contamination
 - Belt loosen
 - Belt broken
 - Pulley broken

Safety in Motion Control

Help to create a safe environment for both people and machines

Eliminate machine down time by not stopping

- Adjustments while running
- Load/unload without stopping
- Utilize safe work zones
- Maintain coordinated motion during stops









Summary

History & evolution

Challenges & Expectations

- Performance, flexibility, innovation
- Close partnership, communication of collaboration

Technology Solutions

- High performance and complete solution
- Flexible, Intelligent, and Integrated

Future trends

• Smaller, faster, and safe

Thank you



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